

Our dataset originates from NOAA’s National Water Level Observation Network (NWLON), spanning 217 stations. Over a five-year period from 2019-2024 the dataset has over 127 million measurements, each taken at six-minute intervals. Our results focus on the station in Nawiliwili, HI (Station ID: 1611400) due to the data being complete with no missing samples, see Figure 2a).

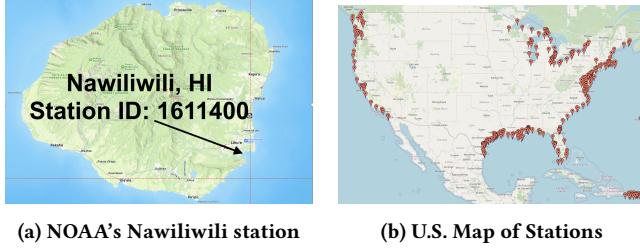


Figure 2: Target station and dataset coverage

We developed a modular pipeline in PyTorch for training and evaluating water-level forecasting models. Each model receives a fixed-length window of prior water levels (7 or 14 days) as input and predicts future water levels at multiple time horizons (1, 3, 5, and 7 days). To understand the importance of exogenous variables in accurate water level forecasting, we examined both univariate and multivariate models. We tested standard Long-Short Term Memory (LSTM) models, bidirectional LSTMs (BiLSTM), convolutional LSTMs (Conv-LSTM), attention-based LSTMs (Attn-LSTM), as well as single and stacked gated recurrent units (GRUs). See Table 1 for hyperparameter grid search values.

Table 1: Hyperparameter grid for univariate model sweep.

| Parameter        | Values Tested                                                |
|------------------|--------------------------------------------------------------|
| Sequence Length  | 7, 14                                                        |
| Batch Size       | 32, 64, 128, 256, 512                                        |
| Learning Rate    | $1 \times 10^{-3}$ , $1 \times 10^{-4}$ , $1 \times 10^{-5}$ |
| Hidden Size      | 32, 64                                                       |
| Number of Layers | 1, 2                                                         |

### 3 PERFORMANCE EVALUATION

Despite the theoretical advantages of BiLSTM, GRUs, and Attention-based LSTMs, we did not observe a significant improvement over standard LSTM models (see Table 2). Performance distributions largely overlapped, suggesting that careful tuning matters more than exotic architecture selection.

Table 2: Forecast performance across architectures

| Model     | Seq. Len | Batch Size | LR     | Hidden Size | Layers | MSE    | MAE    | MaxAE  |
|-----------|----------|------------|--------|-------------|--------|--------|--------|--------|
| ATTN-LSTM | 7        | 32         | 0.001  | 64          | 1      | 0.0033 | 0.0441 | 0.3085 |
| BiLSTM    | 7        | 32         | 0.001  | 32          | 1      | 0.0029 | 0.0409 | 0.2758 |
| Conv-LSTM | 7        | 64         | 0.001  | 32          | 1      | 0.0028 | 0.0400 | 0.2556 |
| GRU       | 7        | 64         | 0.0001 | 64          | 2      | 0.0028 | 0.0402 | 0.2709 |
| LSTM      | 7        | 128        | 0.0005 | 32          | 1      | 0.0028 | 0.0400 | 0.3423 |

For the hyperparameter sweep, we found learning rate to be the dominant factor. Models trained with  $1 \times 10^{-3}$  converged fastest and achieved the highest  $R^2$ , outperforming lower values by a wide margin. Batch size and number of layers had modest effects. Smaller batches (32–64) improved stability and generalization. One or two layers offered comparable results.

Longer sequences (14 vs. 7) slightly improved accuracy but at a significant training time increase. Models tuned for one sequence length also did not generalize well for other sequence lengths.

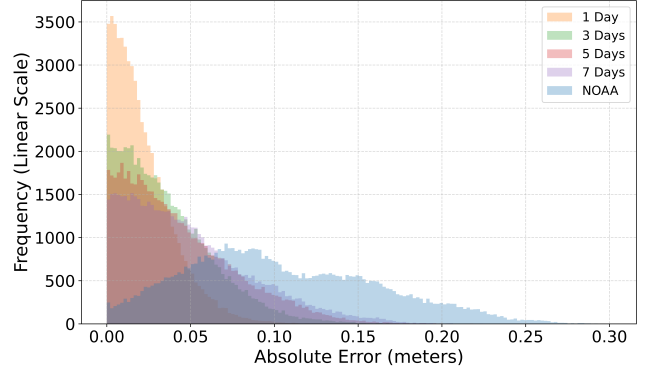


Figure 3: LSTM vs NOAA prediction errors (Nawiliwili station, 2024). LSTM errors provided at 1, 3, 5, and 7 day horizons.

Our best configuration for the LSTM had 1-layer, input sequence of 14-days, 64 batch size, 32 hidden size, and  $1 \times 10^{-3}$  learning rate. Our results show that properly tuned machine learning models outperform the scientific standard harmonics (2.1X with 7 day horizon or 4.7X with 1 day horizon). Figure 3 shows the histogram of all predictions using the LSTM compared to NOAA's predictions, showing the error in meters. These findings align with broader trends in Earth system modeling, where deep learning methods are increasingly surpassing classical statistical and physical models in accuracy and adaptability [4].

### 4 CONCLUSION AND FUTURE WORK

TidalMark demonstrates that well-tuned deep learning architectures can outperform traditional harmonic-based forecasts in dynamic environments. Our results show that properly tuned machine learning models outperform state-of-the-art approaches by 4.7X. We plan to extend TidalMark into a full spatiotemporal Graph Neural Network framework, where each station is a node and edges represent geophysical relationships. Beyond methodological advances, we plan to integrate TidalMark into real-time early flood detection and coastal management systems.

### REFERENCES

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